Rail-to-Rail Output Audio Amplifiers

## SSM2275/SSM2475*

## FEATURES

Single or Dual-Supply Operation
Excellent Sonic Characteristics
Low Noise: $7 \mathbf{n V} / \sqrt{\mathrm{Hz}}$
Low THD: 0.0006\%
Rail-to-Rail Output
High Output Current: $\pm \mathbf{5 0} \mathrm{mA}$
Low Supply Current: 1.7 mA /amplifier
Wide Bandwidth: 8 MHz
High Slew Rate: 12 V/ $\mu \mathrm{s}$
No Phase Reversal
Unity Gain Stable
Stable Parameters Over Temperature

## APPLICATIONS

## Multimedia Audio <br> Professional Audio Systems <br> High Performance Consumer Audio <br> Microphone Preamplifier <br> MIDI Instruments

## GENERAL DESCRIPTION

T he SSM 2275 and SSM 2475 use the Butler Amplifier front end, which combines both bipolar and FET transistors to offer the accuracy and low noise performance of bipolar transistors and the slew rates and sound quality of FETs. This product family includes dual and quad rail-to-rail output audio amplifiers that achieve lower production costs than the industry standard OP275 (the first Butler Amplifier offered by A nalog D evices). T his lower cost amplifier also offers operation from a single 5 V supply, in addition to conventional $\pm 15 \mathrm{~V}$ supplies. The ac performance meets the needs of the most demanding audio applications, with 8 M Hz bandwidth, $12 \mathrm{~V} / \mu \mathrm{s}$ slew rate and extremely low distortion.
The SSM 2275 and SSM 2475 are ideal for application in high performance audio amplifiers, recording equipment, synthesizers, M IDI instruments and computer sound cards. Where cascaded stages demand low noise and predictable performance, SSM 2275 and SSM 2475 are a cost effective solution. Both are stable even when driving capacitive loads.
The ability to swing rail-to-rail at the outputs (see Applications section) and operate from low supply voltages enables designers to attain high quality audio performance, even in single supply systems. The SSM 2275 and SSM 2475 are specified over the extended industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ temperature range and are available in 8 -lead plastic DIPs, SOIC s, and microSOIC surface mount packages. The SSM 2475 is available in 14-lead plastic DIPs, narrow body SOIC s, and thin shrink small outline (TSSOP) surface mount packages.
*Protected by U.S. Patent No. 5,101,126.

## REV. 0

[^0]PIN CONFIGURATIONS


8-Lead microSOIC
(RM-8)


14-Lead Plastic DIP
( N -14)


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## SSM2275/SSM2475- SPECIFICATIONS



| Parameter | Symbol | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT CHARACTERISTICS <br> Offset Voltage <br> Input Bias Current <br> Input Offset Current <br> Input Voltage Range <br> Common-M ode Rejection Ratio <br> $A_{\text {vo }}$ | $V_{0 S}$ <br> $I_{B}$ <br> Ios <br> $V_{\text {IN }}$ <br> CMRR | $\begin{aligned} & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & \mathrm{~V}_{\mathrm{S}}= \pm 15 \mathrm{~V} \\ & -12.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq+12.5 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C}, \\ & -12.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq+12.5 \mathrm{~V} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega,-12 \mathrm{~V} \leq \mathrm{V}_{\mathrm{O}} \leq+12 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & -14 \\ & 80 \\ & 80 \\ & 100 \\ & 80 \end{aligned}$ | $\begin{aligned} & 1 \\ & 1 \\ & 250 \\ & 300 \\ & 5 \\ & 15 \\ & \\ & 100 \\ & \\ & 100 \\ & 240 \\ & 120 \end{aligned}$ | $\begin{aligned} & 4 \\ & 6 \\ & 400 \\ & 500 \\ & 75 \\ & 125 \\ & +14 \end{aligned}$ | mV <br> mV <br> nA <br> nA <br> nA <br> nA <br> V <br> dB <br> $\mathrm{V} / \mathrm{mV}$ <br> $\mathrm{V} / \mathrm{mV}$ <br> $\mathrm{V} / \mathrm{mV}$ |
| OUTPUT CHARACTERISTICS Output Voltage, High Output Voltage, Low Output Short Circuit Current Limit | $\begin{aligned} & \mathrm{V}_{\mathrm{OH}} \\ & \mathrm{~V}_{\mathrm{OL}} \\ & \mathrm{I}_{\mathrm{SC}} \end{aligned}$ | $\begin{aligned} & \mathrm{I}_{\mathrm{L}} \leq 20 \mathrm{~mA} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & \mathrm{I}_{\mathrm{L}}=20 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{L}}=10 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{L}}=10 \mathrm{~mA},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ | 14 <br> 14.5 $\begin{aligned} & \pm 25 \\ & \pm 17 \end{aligned}$ | $\begin{aligned} & 14.5 \\ & 14.7 \\ & -14 \\ & -14.6 \\ & -14.3 \\ & \pm 50 \\ & \pm 40 \end{aligned}$ | $\begin{aligned} & -13.5 \\ & -14.4 \\ & -13.9 \\ & \pm 75 \\ & \pm 80 \end{aligned}$ | V <br> V <br> V <br> V <br> V <br> mA <br> mA |
| POWER SUPPLY <br> Power Supply Rejection Ratio Supply Current/Amplifier | $\begin{aligned} & \text { PSRR } \\ & \mathrm{I}_{\mathrm{SY}} \end{aligned}$ | $\begin{aligned} & \pm 2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{S}} \leq \pm 18 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & \mathrm{~V}_{0}=0 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 85 \\ & 80 \end{aligned}$ | $\begin{aligned} & 110 \\ & 105 \\ & 1.7 \\ & 1.75 \end{aligned}$ | $\begin{aligned} & 2.9 \\ & 3.0 \end{aligned}$ | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~dB} \\ & \mathrm{~mA} \\ & \mathrm{~mA} \end{aligned}$ |
| DYNAMIC PERFORMANCE T otal Harmonic Distortion Slew Rate G ain B andwidth Product Channel Separation | $\begin{aligned} & \text { THD } \\ & \text { SR } \\ & \text { GBW } \\ & \text { CS } \end{aligned}$ | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega, \mathrm{f}=1 \mathrm{kHz}, \mathrm{~V}_{\mathrm{O}}=1 \mathrm{~V}_{\mathrm{RMS}} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega \\| 50 \mathrm{pF} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega, \mathrm{f}=1 \mathrm{kHz} \end{aligned}$ | 9 | $\begin{aligned} & 0.0006 \\ & 12 \\ & 8 \\ & 128 \end{aligned}$ |  | \% <br> V/ $\mu \mathrm{S}$ <br> MHz <br> dB |
| NOISE PERFORMANCE <br> Voltage N oise Spectral Density Current N oise Spectral Density | $\begin{aligned} & e_{n} \\ & i_{n} \end{aligned}$ | $\begin{aligned} & \mathrm{f}>1 \mathrm{kHz} \\ & \mathrm{f}>1 \mathrm{kHz} \end{aligned}$ |  | $\begin{aligned} & 8 \\ & <1 \end{aligned}$ |  | $\begin{aligned} & \mathrm{nV} / \sqrt{\mathrm{Hz}} \\ & \mathrm{pA} / \sqrt{\mathrm{Hz}} \end{aligned}$ |

Specifications subject to change without notice.

## ELECTRICAL CHARACTERISTICS $N_{s}=+5 v, T_{A}=+25^{\circ}, V_{c n}=2.5$ unless otherwise noted)

| Parameter | Symbol | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT CHARACTERISTICS Offset Voltage <br> Input Bias Current <br> Input Offset Current <br> Input Voltage Range Common-M ode Rejection Ratio $A_{\text {vo }}$ | $\begin{aligned} & \mathrm{V}_{O S} \\ & \mathrm{I}_{\mathrm{B}} \\ & \mathrm{I}_{O S} \\ & \mathrm{~V}_{\text {IN }} \\ & C M R R \end{aligned}$ | $\begin{aligned} & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & +0.8 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq+2 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega,-0.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{O}} \leq+4.5 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 0.3 \\ & 25 \\ & 20 \end{aligned}$ | $\begin{aligned} & 1 \\ & 1 \\ & 250 \\ & 300 \\ & 5 \\ & 15 \\ & \\ & 85 \\ & 80 \\ & 60 \\ & 50 \end{aligned}$ | $\begin{aligned} & 4 \\ & 6 \\ & 400 \\ & 500 \\ & 75 \\ & 125 \\ & 4.7 \end{aligned}$ | mV <br> mV <br> nA <br> nA <br> nA <br> nA <br> V <br> dB <br> dB <br> $\mathrm{V} / \mathrm{mV}$ <br> $\mathrm{V} / \mathrm{mV}$ |
| OUTPUT CHARACTERISTICS <br> Output Voltage, High <br> Output Voltage, Low <br> Output Short C ircuit Current Limit | $\begin{aligned} & \mathrm{V}_{\mathrm{OH}} \\ & \mathrm{~V}_{\mathrm{OL}} \\ & \mathrm{I}_{\mathrm{SC}} \end{aligned}$ | $\begin{aligned} & \mathrm{I}_{\mathrm{L}} \leq-15 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{L}} \leq-10 \mathrm{~mA},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \\ & \mathrm{I}_{\mathrm{L}} \leq-15 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{L}} \leq-10 \mathrm{~mA} \\ & \mathrm{I}_{\mathrm{L}} \leq-10 \mathrm{~mA},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{A} \leq+85^{\circ} \mathrm{C} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 4.2 \\ & 4.5 \end{aligned}$ | $\begin{aligned} & 4.5 \\ & 4.8 \\ & 0.6 \\ & 0.3 \\ & 0.7 \\ & 40 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 0.5 \\ & 1.1 \end{aligned}$ | V <br> V <br> V <br> V <br> V <br> mA |
| POWER SUPPLY Supply Current/Amplifier | $\mathrm{I}_{\text {SY }}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \\ & -40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C} \end{aligned}$ |  | $\begin{aligned} & 1.7 \\ & 1.75 \end{aligned}$ | $\begin{aligned} & 2.9 \\ & 3.0 \end{aligned}$ | $\begin{aligned} & \mathrm{mA} \\ & \mathrm{~mA} \end{aligned}$ |
| DYNAMIC PERFORMANCE <br> T otal H armonic Distortion Slew Rate G ain B andwidth Product Channel Separation | $\begin{aligned} & \text { THD } \\ & \text { SR } \\ & \text { GBW } \\ & \text { CS } \end{aligned}$ | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega, \mathrm{f}=1 \mathrm{kHz}, \mathrm{~V}_{\mathrm{O}}=1 \mathrm{~V}_{\mathrm{RMS}} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega \\| 50 \mathrm{pF} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega \\| 10 \mathrm{pF} \\ & \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega, \mathrm{f}=1 \mathrm{kHz} \end{aligned}$ |  | $\begin{aligned} & 0.000 \\ & 12 \\ & 6 \\ & 128 \end{aligned}$ |  | \% <br> $\mathrm{V} / \mu \mathrm{S}$ <br> M Hz <br> dB |
| NOISE PERFORMANCE V oltage N oise Spectral Density Current N oise Spectral Density | $\begin{aligned} & e_{n} \\ & i_{n} \end{aligned}$ | $\begin{aligned} & f>1 \mathrm{kHz} \\ & \mathrm{f}>1 \mathrm{kHz} \end{aligned}$ |  | $\begin{aligned} & 8 \\ & <1 \end{aligned}$ |  | $\begin{aligned} & \mathrm{nV} / \sqrt{\mathrm{Hz}} \\ & \mathrm{pA} / \sqrt{\mathrm{Hz}} \end{aligned}$ |

Specifications subject to change without notice.

| ABSOLUTE MAXIMUM RATINGS ${ }^{1}$ |
| :---: |
| Supply Voltage |
|  |
|  |
| torage T emperatur |
| perating T emperature R ang |
| Junction Temperature R ange. . . . . . . $-65^{\circ}$ |
| Lead T emperature |
| ESD Susceptability |
| NOTES <br> ${ }^{1}$ Stresses above those listed under Absolute M aximum Ratings may cause permanent damage to the device. This is a stress rating only; the functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. <br> ${ }^{2}$ F or supplies less than $\pm 15 \mathrm{~V}$, the input voltage and differential input voltage must be less than $\pm 15 \mathrm{~V}$. |
|  |  |
|  |  |

## ABSOLUTE MAXIMUM RATINGS ${ }^{\mathbf{1}}$

Supply Voltage (V V $_{\text {) }}$. . . . . . . . . . . . . . . . . . . . . . . . . . . . . $\pm 18$ V
Input Voltage ( $\mathrm{V}_{\text {IN }}$ ) . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $\pm 15 \mathrm{~V}$
fferential Input Voltage ${ }^{2}$
Operating $T$ emperature Range ....... $-40^{\circ} \mathrm{C}<T_{A}<+85^{\circ} \mathrm{C}$
Junction Temperature Range. . . . . . . . $-65^{\circ} \mathrm{C}<\mathrm{T}_{5}<+150^{\circ} \mathrm{C}$
ead T emperature R ange (Soldering, 60 sec ) . . . . . . . $+300^{\circ} \mathrm{C}$

NOTES
${ }^{1}$ Stresses above those listed under Absolute M aximum Ratings may cause permanent damage to the device. This is a stress rating only; the functional operation of the device at these or any other conditions above those indicated in the operational conditions for extended periods may affect device reliability.
${ }^{2}$ F or supplies less than $\pm 15 \mathrm{~V}$, the input voltage and differential input voltage must be less than $\pm 15 \mathrm{~V}$.

| Package Type | $\boldsymbol{\theta}_{\mathbf{J A}}{ }^{*}$ | $\boldsymbol{\theta}_{\mathbf{J C}}$ | Units |
| :--- | :--- | :--- | :--- |
| 8-L ead Plastic DIP | 103 | 43 | ${ }^{\circ} \mathrm{C} / W$ |
| 8-Lead SOIC | 158 | 43 | ${ }^{\circ} \mathrm{C} / W$ |
| 8-L ead microSOIC | 206 | 43 | ${ }^{\circ} \mathrm{C} / W$ |
| 14-L ead Plastic DIP | 83 | 39 | ${ }^{\circ} \mathrm{C} / W$ |
| 14-L ead SOIC | 120 | 36 | ${ }^{\circ} \mathrm{C} / W$ |
| 14-L ead TSSOP | 180 | 35 | ${ }^{\circ} \mathrm{C} / W$ |

${ }^{*} \theta_{\mathrm{JA}}$ is specified for the worst case conditions, i.e., for device in socket for DIP packages and soldered onto a circuit board for surface mount packages.

## ORDERING GUIDE

| Model | Temperature <br> Range | Package <br> Description | Package <br> Options |
| :--- | :--- | :--- | :--- |
| SSM 2275P | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 8 -L ead PDIP | $\mathrm{N}-8$ |
| SSM 2275S | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 8 -L ead SOIC | SO-8 |
| SSM 2275RM | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 8 -L ead microSOIC | RM -8 |
| SSM 2475P | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 14-L ead PD IP | $\mathrm{N}-14$ |
| SSM 2475S | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 14 -L ead SOIC | R-14 |
| SSM 2275RU | $-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ | 14 -Lead TSSOP | RU -14 |

## CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the SSM 2275/SSM 2475 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.


Figure 1. Phase/Gain vs. Frequency


Figure 2. Phase/Gain vs. Frequency

## Typical Characteristics- SSM2275/SSM2475



Figure 3. Phase/Gain vs. Frequency


Figure 4. Phase/Gain vs. Frequency


Figure 5. SSM 2275 Current Noise Density vs. Frequency


Figure 6. SSM 2275 Voltage Noise Density (Typical)


Figure 7. Common-Mode Rejection vs. Frequency


Figure 8. Power Supply Rejection vs. Frequency

SSM2275/SSM2475- Typical Characteristics


Figure 9. THD vs. Frequency (FFT)


Figure 10. Small Signal Response; $R_{L}=600 \Omega, C_{L}=0 p F$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 11. Small Signal Response; $R_{L}=600 \Omega, C_{L}=100 \mathrm{pF}$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 12. Headroom ( $V_{O H}$ and $V_{O L}$-to-Rails), $T_{A}=+25^{\circ} \mathrm{C}$


Figure 13. Small Signal Response; $R_{L}=600 \Omega, C_{L}=200 \mathrm{pF}$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 14. Small Signal Response; $R_{L}=600 \Omega, C_{L}=300 \mathrm{pF}$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 15. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=0 p F$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 16. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=100 p F$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 17. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=200 \mathrm{pF}$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 18. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=300 \mathrm{pF}$, $V_{S}= \pm 2.5 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 19. Small Signal Response; $R_{L}=600 \Omega, C_{L}=0 p F$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 20. Small Signal Response; $R_{L}=600 \Omega, C_{L}=100 \mathrm{pF}$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$

SSM2275/SSM2475- Typical Characteristics


Figure 21. Small Signal Response; $R_{L}=600 \Omega, C_{L}=200 \mathrm{pF}$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 22. Small Signal Response; $R_{L}=600 \Omega, C_{L}=300 \mathrm{pF}$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 23. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=0 p F$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 24. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=100 p F$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 25. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=200 \mathrm{pF}$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$


Figure 26. Small Signal Response; $R_{L}=2 k \Omega, C_{L}=300 \mathrm{pF}$, $V_{S}= \pm 15 \mathrm{~V}, A_{V}=+1, V_{I N}=100 \mathrm{mV} p-p$

## THEORY OF OPERATION

The SSM 2275 and SSM 2475 are low noise and low distortion rail-to-rail output amplifiers that are excellent for audio applications. B ased on the OP275 audiophile amplifier, the SSM 2275/ SSM 2475 offers many similar performance characteristics with the advantage of a rail-to-rail output from a single supply source. Its low input voltage noise figure of $7 \mathrm{nV} / \sqrt{\mathrm{Hz}}$ allows the device to be used in applications requiring high gain, such as microphone preamplifiers. Its $11 \mathrm{~V} / \mu \mathrm{s}$ slew rate also allows the SSM 2275/SSM 2475 to produce wide output voltage swings while maintaining low distortion. In addition, its low harmonic distortion figure of $0.0006 \%$ makes the SSM 2275 and SSM 2475 ideal for high quality audio applications.
Figure 27 shows the simplified schematic for a single amplifier. The amplifier contains a Butler Amplifier at the input. This front-end design uses both bipolar and M OSFET transistors in the differential input stage. The bipolar devices, Q1 and Q2, improve the offset voltage and achieve the low noise performance, while the M OS devices, M 1 and M 2, are used to obtain higher slew rates. The bipolar differential pair is biased with a proportional-to-absolute-temperature (PTAT) bias source, IB1, while the M OS differential pair is biased with a non-PT AT source, IB2. This results in the amplifier having a constant gainbandwidth product and a constant slew rate over temperature.
The amplifier also contains a rail-to-rail output stage that can sink or source up to 50 mA of current. As with any rail-to-rail output amplifier the gain of the output stage, and consequently the open loop gain of the amplifier, is proportional to the load resistance. With a load resistance of $50 \mathrm{k} \Omega$, the dc gain of the amplifier is over 110 dB . At load currents less than 1 mA , the output of the amplifier can swing to within 30 mV of either supply rail. As load current increases, the maximum voltage swing of the output will decrease. This is due to the collector to emitter saturation voltage of the output transistors increasing with an increasing collector current.

## Input Overvoltage Protection

The maximum input differential voltage that can be applied to the SSM 2275/SSM 2475 is $\pm 7$ V. A pair of internal back-to-back Zener diodes are connected across the input terminals. T his prevents emitter-base junction breakdown from occurring to the
input transistors, Q1 and Q2, when very large differential voltages are applied. If the device's differential voltage could exceed $\pm 7 \mathrm{~V}$, then the input current should be limited to less than $\pm 5 \mathrm{~mA}$. This can be easily done by placing a resistor in series with both inputs. The minimum value of the resistor can be determined by:

$$
\begin{equation*}
R_{\text {IN }}=\frac{V_{\text {DIFF }, \text { MAX }}-7}{0.01} \tag{1}
\end{equation*}
$$

There are also ESD protection diodes that are connected from each input to each power supply rail. T hese diodes are normally reversed biased, but will turn on if either input voltage exceeds either supply rail by more than 0.6 V . Again, should this condition occur the input current should be limited to less than $\pm 5 \mathrm{~mA}$. The minimum resistor value should then be:

$$
\begin{equation*}
R_{\text {IN }}=\frac{V_{\text {IN , MAX }}}{5 \mathrm{~mA}} \tag{2}
\end{equation*}
$$

In practice, $\mathrm{R}_{\mathrm{IN}}$ should be placed in series with both inputs to reduce offset voltages caused by input bias current. This is shown in Figure 28.


Figure 28. Using Resistors for Input Overcurrent Protection

## Output Voltage Phase Reversal

The SSM 2275/SSM 2475 was designed to have a wide commonmode range and is immune to output voltage phase reversal with an input voltage within the supply voltages of the device. H owever, if either of the device's inputs exceeds 0.6 V above the posi-


Figure 27. Simplified Schematic

## SSM2275/SSM2475

tive voltage supply, the output could exhibit phase reversal. T his is due to the input transistor's B-C junction becoming forward biased, causing the polarity of the input terminals of the device to switch.
This phase reversal can be prevented by limiting the input current to +1 mA . This can be done by placing a resistor in series with the input terminal that is expected to be overdriven. The series resistance should be at least:

$$
\begin{equation*}
R_{\text {IN }}=\frac{V_{\text {IN , MAX }}-0.6}{1 \mathrm{~mA}} \tag{3}
\end{equation*}
$$

An equivalent resistor should be placed in series with both inputs to prevent offset voltages due to input bias currents, as shown in Figure 28.

## Output Short Circuit Protection

To achieve high quality rail-to-rail performance, the output of the SSM 2275/SSM 2475 is not short-circuit protected. Shorting the output may damage or destroy the device when excessive voltages or currents are applied. T o protect the output stage, the maximum output current should be limited to $\pm 40 \mathrm{~mA}$. Placing a resistor in series with the output of the amplifier as shown in Figure 29, the output current can be limited. The minimum value for $\mathrm{R}_{\mathrm{x}}$ can be found from Equation 4.

$$
\begin{equation*}
\mathrm{R}_{\mathrm{X}}=\frac{\mathrm{V}_{\mathrm{SY}}}{40 \mathrm{~mA}} \tag{4}
\end{equation*}
$$

For $\mathrm{a}+5 \mathrm{~V}$ single supply application, $\mathrm{R}_{\mathrm{x}}$ should be at least $125 \Omega$. Because $R_{X}$ is inside the feedback loop, $\mathrm{V}_{\text {OUt }}$ is not affected. The trade off in using $R_{x}$ is a slight reduction in output voltage swing under heavy output current loads. $\mathrm{R}_{\mathrm{x}}$ will also increase the effective output impedance of the amplifier to $R_{0}+R_{x}$, where $R_{0}$ is the output impedance of the device.


Figure 29. Output Short Circuit Protection Configuration

## Power Dissipation Considerations

While many designers are constrained to use very small and low profile packages, reliable operation demands that the maximum junction temperatures not be exceeded. A simple calculation will ensure that your equipment will enjoy reliable operation over a long lifetime. M odern IC design allows dual and quad amplifiers to be packaged in SOIC and microSOIC packages, but it is the responsibility of the designer to determine what the actual junction temperature will be, and prevent it from exceeding the $150^{\circ} \mathrm{C}$. N ote that while the $\theta_{\mathrm{Jc}}$ is similar between package options, the $\theta_{\mathrm{JA}}$ for the SOIC and TSSOP are nearly double the P-DIP. The calculation of maximum ambient temperature is relatively simple to make.

$$
\begin{equation*}
\mathrm{P}_{\mathrm{MAX}}=\frac{\mathrm{T}_{1, \mathrm{MAX}}-\mathrm{T}_{\mathrm{A}}}{\theta_{\mathrm{JA}}} \tag{5}
\end{equation*}
$$

F or example, with the 8-lead SOIC, the calculation gives a maximum internal power dissipation (for all amplifiers, worst case) of $\mathrm{P}_{\text {MAX }}=\left(150^{\circ} \mathrm{C}-85^{\circ} \mathrm{C}\right) / 158^{\circ} \mathrm{C} / \mathrm{W}=0.41 \mathrm{~W}$. F or the DIP package, a similar calculation indicates that 0.63 W (approximately $50 \%$ more) can be safely dissipated. N ote that ambient temperature is defined as the temperature of the PC board to which the device is connected (in the absence of radiated or convected heat loss). It is good practice to place higher power devices away from the more sensitive circuits. When in doubt, measure the temperature in the vicinity of the SSM 2275 with a thermocouple thermometer.

## Maximizing Low Distortion Performance

Because the SSM 2275/SSM 2475 is a very low distortion amplifier, careful attention should be given to the use of the device to prevent inadvertently introducing distortion. Source impedances seen by both inputs should be made equal, as shown in Figure 28, with $R_{B}=R 1 \| R_{F}$ for minimum distortion. This eliminates any offset voltages due to varying bias currents. Proper power supply decoupling reduces distortion due to power supply variations.
Because the open loop gain of the amplifier is directly dependent on the load resistance, loads of less than $10 \mathrm{k} \Omega$ will increase the distortion of the amplifier. This is a trait of any rail-to-rail op amp. Increasing load capacitance will also increase distortion.
It is recommended that any unused amplifiers be configured as a unity gain follower with the noninverting input tied to ground. This minimizes the power dissipation and any potential crosstalk from the unused amplifier.
As with many FET-type amplifiers, the PM OS devices in the input stage exhibit a gate-to-source capacitance that varies with the common mode voltage. In an inverting configuration, the inverting input is held at a virtual ground and the common-mode voltage does not vary. This eliminates distortion due to input capacitance modulation. In noninverting applications, the gate-to-source voltage is not constant, and the resulting capacitance modulation can cause a slight increase in distortion.
Figure 30 shows a unity gain inverter and a unity gain follower configuration. Figure 31 shows an FFT of the outputs of these amplifiers with a 1 kHz sine wave. N otice how the largest harmonic amplitude (2nd harmonic) is -120 dB below the fundamental $(0.0001 \%)$ in the inverting configuration.


Figure 30. Basic Inverting and Noninverting Amplifiers


Figure 31. Spectral Graph of Amplifier Outputs

## Settling Time

The high slew rate and wide gain-bandwidth product of the SSM 2275 and SSM 2475 amplifiers result in fast settling times ( $\mathrm{t}_{\mathrm{s}}<1 \mu \mathrm{~s}$ ) that are suitable for 16 and 20 -bit applications. The test circuit used to measure the settling time of the SSM 2275/ SSM 2475 is shown in Figure 32. T his test method has advantages over false-sum node techniques of measuring settling times in that the actual output of the amplifier is measured, instead of an error voltage at the sum node. Common-mode settling effects are also taken into account in this circuit in addition to slew rate and bandwidth factors.
The output waveform of the device under test is clamped by Schottky diodes and buffered by the JFET source follower. The signal is amplified by a factor of ten by the OP260 current feedback amplifier and then Schottky-clamped at the output to the oscilloscope. The 2 N 2222 transistor sets up the bias current for the JFET and the OP41 is configured as a fast integrator, providing overall dc offset nulling at the output.


Figure 33. Settling Time vs. Step Size

## Overdrive Recovery

The overdrive, or overload, recovery time of an amplifier is the time required for the output voltage to return to a rated output voltage from a saturated condition. This recovery time can be important in applications where the amplifier must recover quickly after a large transient event, or overload. The circuit in Figure 34 was used to evaluate the recovery time for the SSM 2275/SSM 2475 . Also shown are the input and output voltages. It takes approximately $0.5 \mu \mathrm{~s}$ for the device to recover from output overload.


Figure 34. Overload Recovery Time Test Circuit


Figure 32. Settling Time Test Fixture

## Capacitive Loading

The output of the SSM 2275/SSM 2475 can tolerate a degree of capacitive loading. H owever, under certain conditions, a heavy capacitive load could create excess phase shift at the output and put the device into oscillation. The degree of capacitive loading is dependent on the gain of the amplifier. At unity gain, the amplifier could become unstable at loads greater than 600 pF . At gain greater than unity, the amplifier can handle a higher degree of capacitive load without oscillating. Figure 35 shows how to configure the device to prevent oscillations from occurring.


INVERTING GAIN AMPLIFIER

noninverting gain amplifier

Figure 35. Configurations for Driving Heavy Capacitive Loads
$R_{B}$ should be at least $50 \mathrm{k} \Omega$. To minimize offset voltage, the parallel combination of $R_{F B}$ and $R_{\text {, }}$ should be equal to $R_{B}$. Setting a minimum $C_{F}$ of 15 pF bandlimits the amplifier enough to eliminate any oscillation problems from any sized capacitive load. The low-pass frequency is determined by:

$$
\begin{equation*}
f_{-3 d B}=\frac{1}{2 \pi R_{F B} C_{F}} \tag{6}
\end{equation*}
$$

With $\mathrm{R}_{\mathrm{FB}}=50 \mathrm{k} \Omega$ and $\mathrm{C}_{\mathrm{F}}=15 \mathrm{pF}$, this results in an amplifier with a 210 kHz bandwidth that can be used with any capacitive load. If the amplifier is being used in a non-inverting unity gain configuration and $R_{l}$ is omitted, $C_{F B}$ should be at least 100 pF . If the offset voltage can be tolerated at the output, $\mathrm{R}_{\mathrm{FB}}$ can be replaced by a short and $C_{F B}$ can be removed entirely. With the typical input bias current of 200 nA and $\mathrm{R}_{\mathrm{B}}=50 \mathrm{k} \Omega$, the increase in offset voltage would be 10 mV . This configuration will stabilize the amplifier under all capacitive loads.

## Single Supply Differential Line Driver

Figure 36 shows a single supply differential line driver circuit that can drive a $600 \Omega$ load with less than $0.001 \%$ distortion. The design mimics the performance of a fully balanced transformer based solution. H owever, this design occupies much less board space while maintaining low distortion and can operate down to dc. Like the transformer based design, either output can be shorted to ground for unbalanced line driver applications without changing the circuit gain of 1 .
R13 and R14 set up the common-mode output voltage equal to half of the supply voltage. C1 is used to couple the input signal and can be omitted if the input's dc voltage is equal to half of the supply voltage. The minimum input impedance of the circuit as seen from $\mathrm{V}_{\text {IN }}$ is:

$$
\begin{equation*}
R_{\text {IN }}=(R 1+R 5)\|(R 3+R 7)\| R 11 \tag{7}
\end{equation*}
$$

F or the values given in Figure $36, \mathrm{R}_{\mathrm{IN}}=5 \mathrm{k} \Omega$. With C 1 omitted the circuit will provide a balanced output down to dc, otherwise the -3 dB corner for the input frequency is set by:

$$
\begin{equation*}
\mathrm{f}_{-3 \mathrm{~dB}}=\frac{1}{2 \pi \mathrm{R}_{\mathrm{IN}} C_{\mathrm{L}}} \tag{8}
\end{equation*}
$$

The circuit can also be configured to provide additional gain if desired. The gain of the circuit is:

$$
\begin{equation*}
A_{V}=\frac{V_{\text {OUT }}}{V_{\text {IN }}}=\frac{2(R 2)}{R 1} \tag{9}
\end{equation*}
$$

where $\mathrm{V}_{\text {OUT }}=\mathrm{V}_{01}-\mathrm{V}_{02}, \mathrm{R} 1=\mathrm{R} 3=\mathrm{R} 5=\mathrm{R} 7$ and, $R 2=R 4=R 6=R 8$

Figure 37 shows the THD +N versus frequency response of the circuit while driving a $600 \Omega$ load at 1 V rms.


Figure 36. A Low Noise, Single Supply Differential Line Driver


Figure 37. THD $+N$ vs. Frequency of Differential Line Driver

## Multimedia Soundcard Microphone Preamplifier

The low distortion and low noise figures of the SSM 2275 make it an excellent device for amplifying low level audio signals. Figure 38 shows how the SSM 2275 can be configured as a stereo microphone preamplifier driving the input to a multimedia sound codec, the AD 1848. T he SSM 2275 can be powered from the same +5 V single supply as the $A D 1848$. The $\mathrm{V}_{\text {REF }}$ pin on the AD 1848 provides a bias voltage of 2.25 V for the SSM 2275. This voltage can also be used to provide phantom power to a condenser microphone through a 2N 4124 transistor buffer and $2 \mathrm{k} \Omega$ resistors. The phantom power circuitry can be omitted for dynamic microphones. The gain of SSM 2275 amplifiers is set by $R 2 / R 1$ which is $100(40 \mathrm{~dB})$ as shown. Figure 39 shows the device's THD +N performance with a $1 \mathrm{~V}_{\text {RMS }}$ output.


Figure 38. Low Noise Microphone Preamplifier for Multimedia Soundcard Codec


Figure 39. $T H D+N$ vs. Frequency $\left(V_{S Y}=+5 V, A_{V}=40 d B\right.$, $V_{\text {OUT }}=1 \mathrm{~V}$ rms)
High Performance I-V Converters and Filters for 20-Bit DACs Because of the increasing resolution and lower harmonic distortions required by more audio applications, the need for high quality amplifiers at the output of D/A converters becomes critical. T he SSM 2275 and SSM 2475 can be used as current-tovoltage converters and smoothing filters for 18- and 20-bit DACs, achieving $0.0006 \%$ THD +N figures while running from the same +5 V or +12 V source used to power the $\mathrm{D} / \mathrm{A}$ converter. Figure 40 shows how the SSM 2275 can be used with the AD 1862, a current output 20-bit D AC.

The AD 1862 has a built in $3 \mathrm{k} \Omega$ resistor that is connected from the inverting input to the output of the amplifier. T he full-scale output current of the AD 1862 is $\pm 1 \mathrm{~mA}$, resulting in a maximum output voltage of $\pm 3 \mathrm{~V}$. Additional feedback resistance can be added in the feedback loop to increase the output voltage. With $\mathrm{R}_{\mathrm{FB}}$ connected the maximum output voltage will be:

$$
\begin{equation*}
\mathrm{V}_{\text {OUT }, \mathrm{MAX}}=1 \mathrm{~mA} \times\left(3 \mathrm{k} \Omega+\mathrm{R}_{\mathrm{FB}}\right) \tag{10}
\end{equation*}
$$



NOTE: ADDITIONAL PIN CONNECTIONS OMITTED FOR CLARITY
Figure 40. A High Performance I-V Converter for a 20-Bit DAC In F igure 41, the SSM 2275 is used as a low-pass filter for one channel of the AD 1855, a 24-bit 96 kH z stereo sigma-delta DAC, which uses a complementary voltage output. The filter is configured as a second order low-pass Bessel filter with a cutoff frequency of 50 kHz . This provides a phase linear response from dc to 24 kHz , which is ideal for high quality audio applications. The SSM 2275 can be connected to the same +5 V power supply source, that the AD 1855 is connected to, eliminating the need for extra power circuitry. The FILT output (Pin 14) from the AD 1855 provides a common reference voltage equal to half of the supply voltage for the SSM 2275.
Amplifier A1 is used as a unity-gain inverter for the positive output of the AD 1855. The output of A1 is combined with a negative output of the AD 1855 into the active low pass filter around A2. The output impedance of each output of the AD 1855 is $100 \Omega$ which must be taken into account to achieve proper dc gain, which in Figure 41 is unity gain. In this configuration the SSM 2275 can drive reasonable capacitive loads, making the device suitable for the RCA jack line outputs found in most consumer audio equipment.


Figure 41. Low-Pass Filter for a 24-Bit Stereo SigmaDelta DAC


Figure 42. A Smoothing Filter for an 18-Bit Stereo DAC

## SPICE Macro-model

The SPICE macro-model for the SSM 2275 is shown in Listing 1 on the following page. This model is based on typical values for the device and can be downloaded from A nalog D evices' Internet site at www.analog.com. The model uses a common emitter output stage to provide rail-to-rail performance. A resistor and dc voltage source, in series with the collector, accurately portray output dropout voltage versus output current. T he VCM H and VCM L sources set the upper and lower limits of
the input common mode voltage range. Both are set up as a function of the supply voltage to mimic the varying common mode range with supply voltage. The EOS voltage source establishes the offset voltage and is also used to create the commonmode rejection and power supply rejection characteristics for the model.
A secondary pole section is also set up to vary the gain bandwidth product and phase margin of the model based on the supply voltage. The H 1 and VR 1 sources set up an equivalent resistor that is linearly varied with supply voltage. T his equivalent resistance, in parallel with C 2 , creates the secondary pole. G 2 is also linearly varied to increase the GBW at higher supply voltages. With a supply voltage of 5 V , the gain bandwidth product is 6.3 M Hz with a 47 degree phase margin. At a 30 V supply voltage, the GBW product moves out to 7.5 M Hz with $48^{\circ}$ phase margin.
The broadband input referred voltage noise for the model is $6.8 \mathrm{nV} / \sqrt{\mathrm{Hz}}$. Flicker noise characteristics are also accurately modeled with the $1 / \mathrm{f}$ corner frequency set through the K F and AF terms in the input stage transistors. Finally, a voltage-controlled current source, GSY, is used to model the amplifier's supply current versus supply voltage characteristics.

## Listing 1: SSM2275 SPICE Macro-Model

* SSM2275 SPICE Macro-Model Typical Values
* 8/97, Ver. 1
* TAM / ADSC
* 
* Node assignments
$\star$
$\star$
$\star$
. SUBCKT SSM2275
* 
* INPUT STAGE
* 

Q1 435 QNIX
Q2 $\quad 6 \quad 2 \quad 7$ QNIX
RC1 9911 15E3
RC2 9912 15E3
RE1 58 1E3
RE2 78 1E3
EOS 31 POLY (2) $(61,98)(73,98) 1.5 \mathrm{E}-31.78 \mathrm{E}-51$
IOS 12 5E-9
ECMH1 411 POLY(1) $(99,50) 0.9-30 \mathrm{E}-3$
ECMH2 612 POLY (1) $(99,50) 0.9-30 \mathrm{E}-3$
ECML1 950 POLY(1) $(99,50) 0.130 \mathrm{E}-3$
ECML2 1050 POLY (1) $(99,50) 0.130 \mathrm{E}-3$
D1 95 DX
D2 $10 \quad 7 \mathrm{DX}$
D3 $\quad 131 \mathrm{DZ}$
D4 213 DZ
IBIAS 850 200E-6
*

* CMRR=115 dB, ZERO AT 1 kHz , POLE AT 10 kHz
* 

ECM1 6098 POLY (2) $(1,98)(2,98) 0.5 .5$
RCM1 6061 159.2E3
RCM2 619817.66 E 3
CCM1 6061 1E-9
*

* PSRR=120dB, ZERO AT 1 kHz
* 

RPS1 70 0 1E6
RPS2 71 0 1E6
CPS1 9970 1E-5
CPS2 5071 1E-5
EPSY 9872 POLY(2) $(70,0)(0,71) 011$
RPS3 7273 1.59E6
CPS3 7273 1E-10
RPS4 73981.59
*

* INTERNAL VOLTAGE REFERENCE
* 

RSY1 9991 100E3
RSY2 5090 100E3
VSN1 9190 DC 0
EREF $980(90,0) 1$
GSY 9950 POLY (1) $(99,50) 0.97 \mathrm{E}-3-7 \mathrm{E}-6$
*

* ADAPTIVE POLE AND GAIN STAGE
* AT Vsy=5, $\mathrm{fp}=12.50 \mathrm{MHz}, \mathrm{Av}=1$
* AT Vsy=30, fp=18.75MHz, Av=1.16
* 

G2 $9820 \operatorname{POLY}(2)(4,6)(99,50) 080.3 \mathrm{E}-6002.79 \mathrm{E}-6$
VR1 2021 DC 0
H1 2198 POLY(2) VR1 VSN1 0 11.317E3 $00-28.29 E 6$
C2 $20981.2 \mathrm{E}-12$
*

* POLE AT 90 MHz
* 

G3 $9823(20,98) 565.5 \mathrm{E}-6$
R5 23981.768 E 3
C3 $23981 \mathrm{E}-12$
*

* GAin StAGE
* 

G1 $9830(23,98) 733.3 \mathrm{E}-6$
R1 $30989.993 E 3$
CF 3045 200E-12
D5 3199 DX
D6 5032 DX
V1 31300.6
V2 30320.6
*

* OUTPUT STAGE
* 

Q3 464299 QPOX
Q4 474450 QNOX
RO1 464830
RO2 474930
Vo1 4548 15E-3
VO2 4945 10E-3
RB1 4142200
RB2 4344200
EO1 9941 POLY (1) $(98,30) 0.75281$
EO2 4350 POLY (1) $(30,98) 0.75281$
*

* MODELS
* 

.MODEL QNIX NPN ( $I S=1 \mathrm{E}-16, \mathrm{BF}=400, \mathrm{KF}=1.96 \mathrm{E}-14, \mathrm{AF}=1$ )
.MODEL QNOX NPN ( $I S=1 E-16, B F=100, V A F=130$ )
.MODEL QPOX PNP ( $I S=1 E-16, B F=100, V A F=130$ )
.MODEL DX D (IS=1E-16)
.MODEL DZ D (IS=1E-14, BV=6.6)
.ENDS SSM2275

## OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).



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